

**IV B.Tech I Semester Regular Examinations, November 2005**  
**OPTIMIZATION TECHNIQUES**  
**(Electrical & Electronic Engineering)**

Time: 3 hours

Max Marks: 80

Answer any FIVE Questions  
 All Questions carry equal marks

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1. (a) What are the different types of optimization problems? Explain each with the help of suitable objective function and constraints. [8]  
 (b) If  $f(x)$  is optimal at  $x=x^*$ , show that the first maximum varying even derivative  $f(x)$  at  $x=x^*$  must be positive for  $f(x^*)$  to be minimum. [8]
2. (a) State and explain Kuhn-Tucker conditions. [8]  
 (b) Use Kuhn-Tucker conditions to solve the following problem [8]  
 Maximise  $Z = 2x_1^2 + 12x_1x_2 - 7x_2^2$   
 Subject to  $2x_1 + 5x_2 \leq 98$   
 $x_1, x_2 \geq 0$
3. (a) State and explain the standard form of LPP. [8]  
 (b) Explain the significance of slack, surplus and artificial variables of LPP. [8]
4. Solve the following LPP using simplex method

$$\text{maximize } Z = -x_1 + 2x_2$$

$$\text{subject to } x_1 + 2x_2 \leq 4$$

$$2x_1 + 5x_2 \leq 10 \quad [16]$$

5. (a) Discuss the techniques used to solve the transportation problem [6]  
 (b) Solve the following transportation problem [10]

D \ O	A	B	C	Availability
X	500	300	2200	1
Y	900	450	1700	3
Z	2500	2000	500	4

Requirement      4      2      2      8

6. Show that the function  $f(x)=x_2$ ,  $0 \leq x \leq 1$ ,  $f(x)=2-x$ ,  $0 \leq x \leq 1$ , is unimodel in (0,2). Use the Fibonacci method to find its maximal point with in an interval of uncertainty 0.1. [16]
7. Minimize  $f = 3x_1^2 + 4x_2^2$  subject to  $x_1 + 2x_2 = 8$  using an exterior penalty function method with the calculus method of unconstrained minimization. [16]
8. Explain the concept of dynamic programming and show how to solve a linear programming problem by dynamic programming approach with an example. [16]

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