

**IV B.Tech. I Semester Regular Examinations, November -2005**  
**COMPUTER AIDED ANALYSIS & DESIGN**  
**(Civil Engineering)**

Time: 3 hours

Max Marks: 80

**Answer any FIVE Questions**  
**All Questions carry equal marks**

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1. Explain concepts of engineering analysis in computer aided system. [16]
2. Explain various features of computer modelling. [16]
3. Explain software configuration of a graphic system. [16]
4. Write short notes on the following: [4 × 4 = 16]
  - (a) Member stiffness and structure stiffness
  - (b) Transformation matrix
  - (c) Equivalent joint loads
  - (d) Degrees of freedom
5. (a) Explain pivotal distance and its significance. Explain with suitable examples its influence on the final solution. [6]  
 (b) Derive general expression for second order difference terms with unequal spaced pivotal points. [10]
6. Explain the procedure for solution of settlement under a raft foundation using finite difference method. Discuss the effect of closely spaced pivotal points. [16]
7. Maximize  $F = x_1 + 2x_2 + x_3$  subject to
 
$$2x_1 + x_2 - x_3 \leq 2, \quad -2x_1 + x_2 - 5x_3 \geq -6$$

$$4x_1 + x_2 + x_3 \leq 6, \quad x_i \geq 0, i = 1, 2, 3. \quad [16]$$
8. Solve the following simple linear programming problem by Revised simplex method.  
 Maximize  $z = 2x_1 + x_2$   
 Subject to  $3x_1 + 4x_2 \leq 6$   

$$6x_1 + x_2 \leq 3,$$

$$x_1, x_2 \geq 0. \quad [16]$$

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1. What are the various benefits of Computer Aided Design? [16]
2. What are the various hardware features of Computer Aided Design system? [16]
3. Explain software configuration of a graphic system. [16]
4. (a) Write down the transformation matrix for the stress resultants in the local coordinate system to the global coordinate system for a plane frame members. [8]  
 (b) Explain how the overall joint stiffness matrix is obtained and indicate the use of the various sub matrices in the overall joint stiffness matrix. [8]
5. Explain with governing differential equations various applications which can be solved using finite difference method. [16]
6. Explain the procedure for solution of settlement under a raft foundation using finite difference method. Discuss the effect of closely spaced pivotal points. [16]
7. Minimize  $f = -3x_1 - 2x_2$  subject to  
 $x_1 - x_2 \leq 1, \quad 3x_1 - 2x_2 \leq 6, \quad x_1 \geq 0, x_2 \geq 0.$  [16]
8. Solve by the revised simplex method.  
 Maximize  $z = 6x_1 - 2x_2 + 3x_3$   
 Subject to  $2x_1 - x_2 + 2x_3 \leq 2$   
 $x_1 + 4x_3 \leq 4, \quad x_1, x_2, x_3 \geq 0.$  [16]

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1. Explain typical features of a central processing unit used in Computer Aided Design. [16]
2. Explain typical configuration of hardware components in stand-alone Computer Aided Design system. [16]
3. A point in two dimensions is located at (3, 4). It is desired to relocate the point by means of rotation and scaling transformations only (no translation) to a new position defined by (0,8).
  - (a) Describe the sequence of transformations required to accomplish the movement of line as specified.
  - (b) Write transformation matrix for each step in the sequence.
  - (c) Write concatenation transformation matrix for the sequence. [8+4+4]
4. Three wires OA, OB and OC in one plane are hinged at the ends A, B and C and are pin connected at O. Wires OA and OC are inclined to the vertical at  $30^\circ$  and OB is vertical. Length OB = 1.5 m. The three wires jointly support a load of 120 kN at O. The area of cross section of wire OA is  $4 \text{ mm}^2$ , that of OB is  $6 \text{ mm}^2$  and of OC is  $8 \text{ mm}^2$ . If E is constant, determine the forces in the wires using stiffness matrix approach. [16]
5. Explain the effect of boundary conditions and their influence on the deflected shape of the beam. [16]
6. Explain the procedure for solution of settlement under a raft foundation using finite difference method. Discuss the effect of closely spaced pivotal points. [16]
7. Minimize  $f = -40x_1 - 100x_2$  subject to
 
$$\begin{aligned} 10x_1 + 5x_2 &\leq 2500, & 4x_1 + 10x_2 &\leq 2000, \\ 2x_1 + 3x_2 &\leq 900, & x_1 &\geq 0, \quad x_2 \geq 0. \end{aligned}$$
 [16]
8. (a) What are the advantages of Revised simplex method over the Standard simplex method. [6]
- (b) Apply the principle of duality to solve the L.P. problem.  
 Maximize  $z = 3x_1 - 2x_2$   
 Subject to the constraints
 
$$\begin{aligned} x_1 + x_2 &\leq 5, & x_1 &\leq 4 \\ 1 \leq x_2 &\leq 6, & x_1, x_2 &\geq 0. \end{aligned}$$
 [10]

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1. Describe some common editing features available in Computer Aided Design system. [16]
2. Explain the features of workstation used for Computer Aided Design. [16]
3. A line is defined by its end points (0, 0) and (2, 3) in a two dimensional graphics system. It is desired to move this line by means of series of transformation so that its end points will be at (0, 1) and (0, 5).
  - (a) Describe the sequence of transformations required to accomplish the movement of line as specified.
  - (b) Write transformation matrix for each step in the sequence.
  - (c) Write concatenation transformation matrix for the sequence. [16]
4. A rigid portal frame ABC is fixed at A and hinged at C. Member AB is horizontal and is 4 m long. Its moment of Inertia is  $2I$ . Member BC is vertical and 5 m high. Its moment of inertia is  $3I$ . Generate the stiffness matrix of the frame considering the unknowns at B and C. [16]
5. Derive expressions for governing boundary conditions to be incorporated in differential equation terms of a beam with
  - (a) Fixed boundary
  - (b) Simply supported
  - (c) Free end. [16]
6. Explain the procedure for solution of settlement under a raft foundation using finite difference method. Discuss the effect of closely spaced pivotal points. [16]
7. Minimize  $f = 2x_1 + 3x_2 + 2x_3 - x_4 + x_5$  subject to the constraints
 
$$3x_1 - 3x_2 + 4x_3 + 2x_4 - x_5 = 0$$

$$x_1 + x_2 + x_3 + 3x_4 + x_5 = 2$$
 and  $x_i \geq 0, i=1$  to  $5$ . Use two-phase simplex method. [16]
8. Given the linear programming problem :
 

Maximize  $z = 3x_1 + 5x_2$

Subject to the constraints  $3x_1 + 2x_2 \leq 18, x_1 \leq 4$

$$x_2 \leq 6, x_1, x_2 \geq 0.$$

- (a) Determine an optimum solution to the L.P. problem
- (b) Discuss the effect on the optimality of the solution when the objective function is changed to  $z = 3x_1 + x_2$ . [8+8]

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